

FIG. 1C

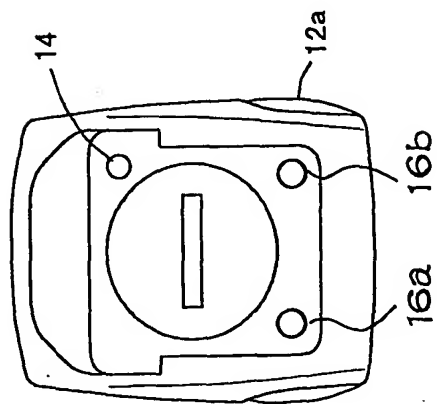


FIG. 1A

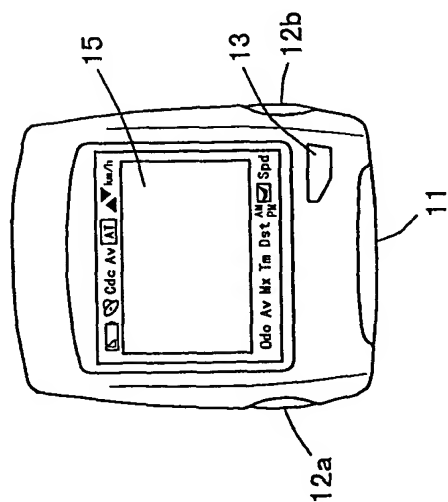
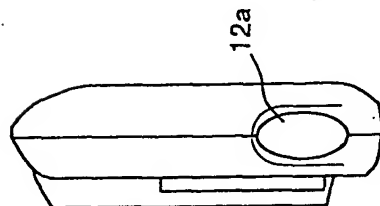


FIG. 1B



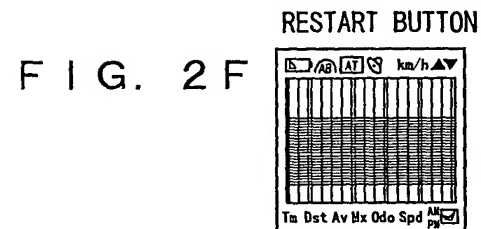
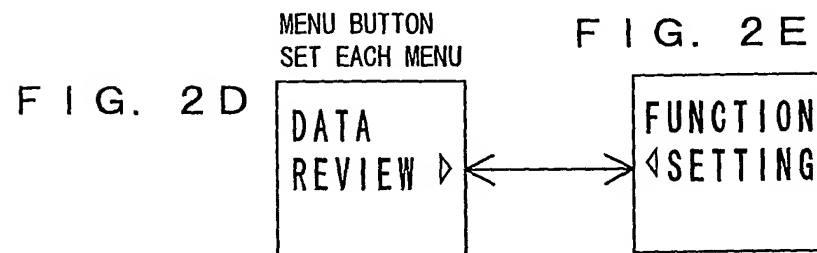
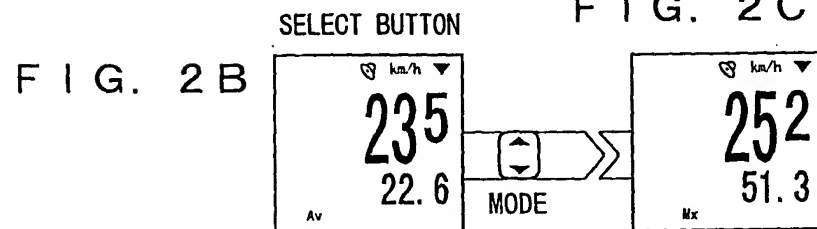
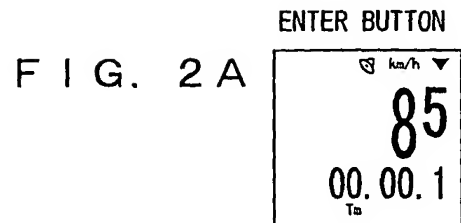


FIG. 3

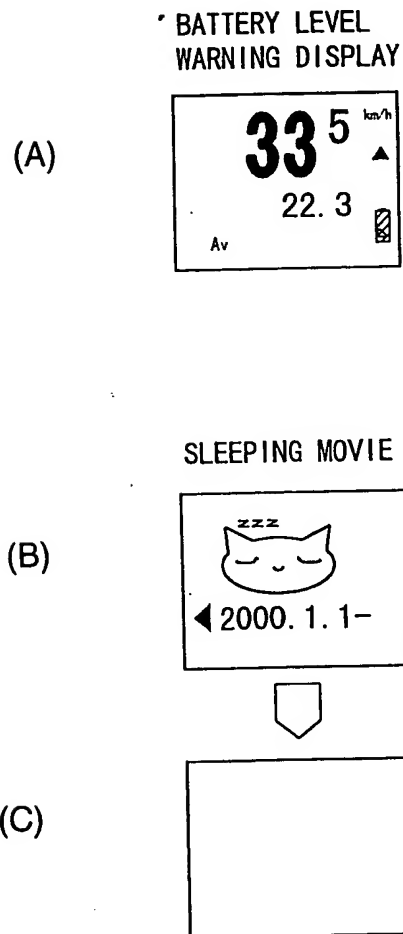


FIG. 4

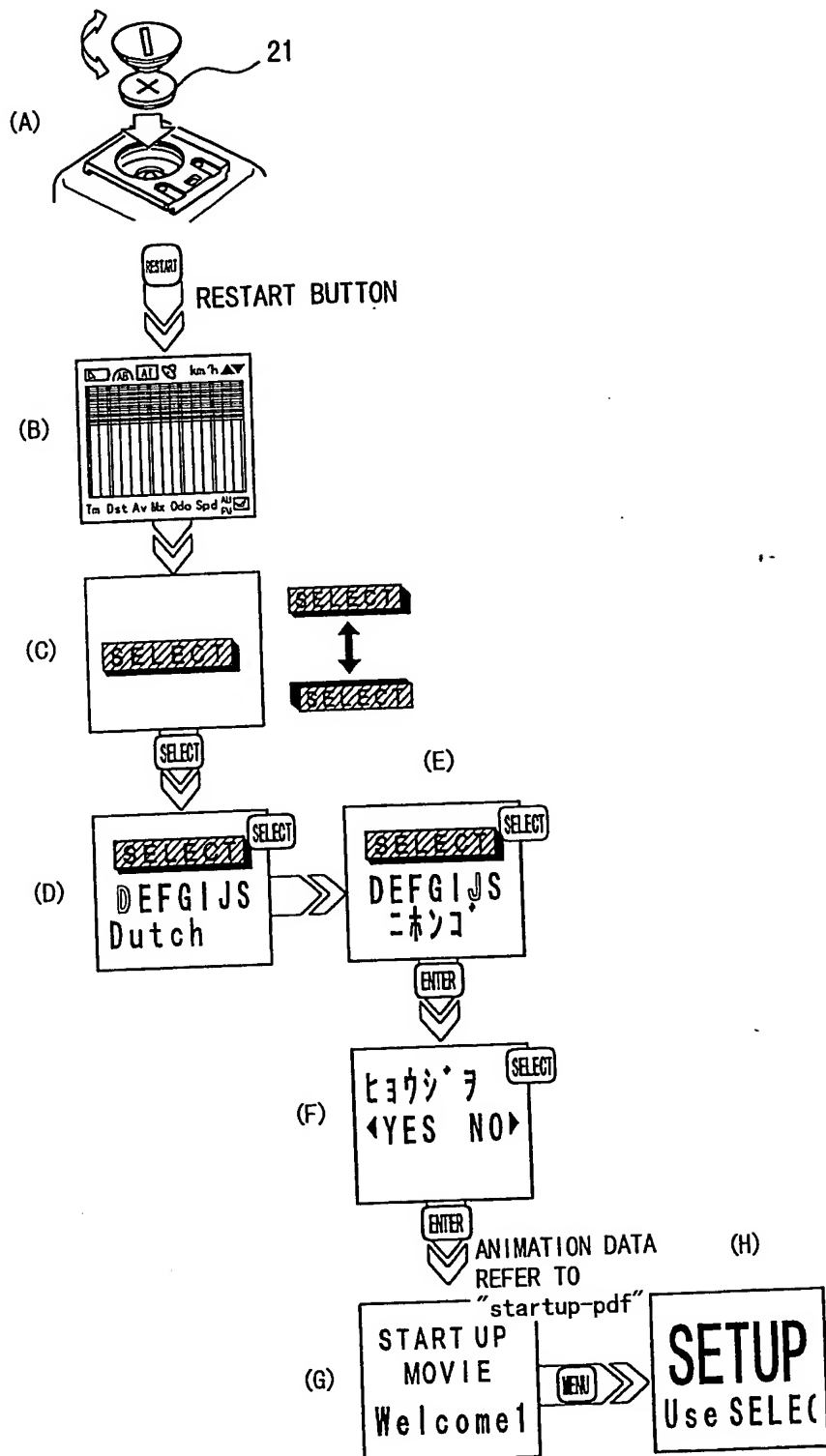


FIG. 5

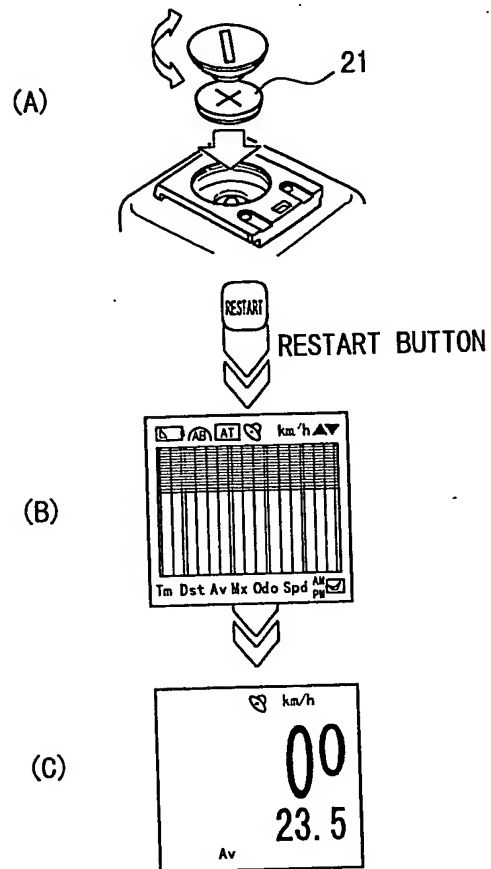


FIG. 6

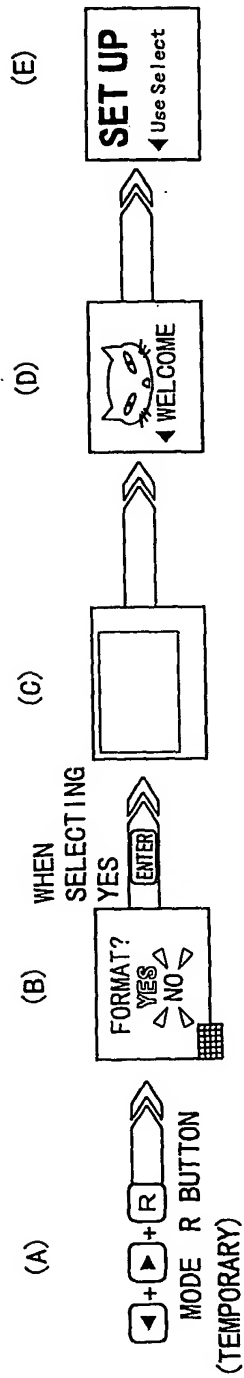


Fig. 7

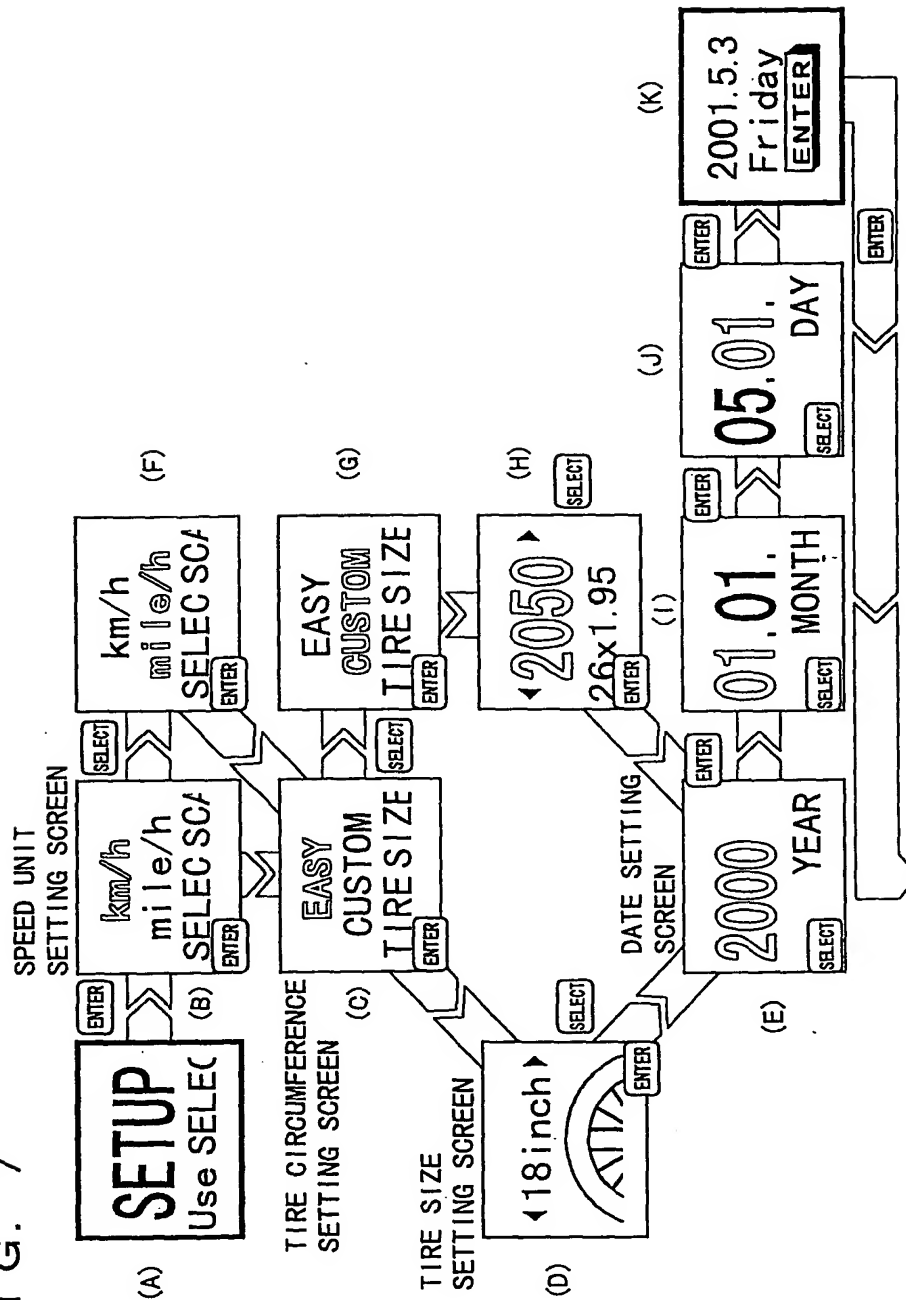
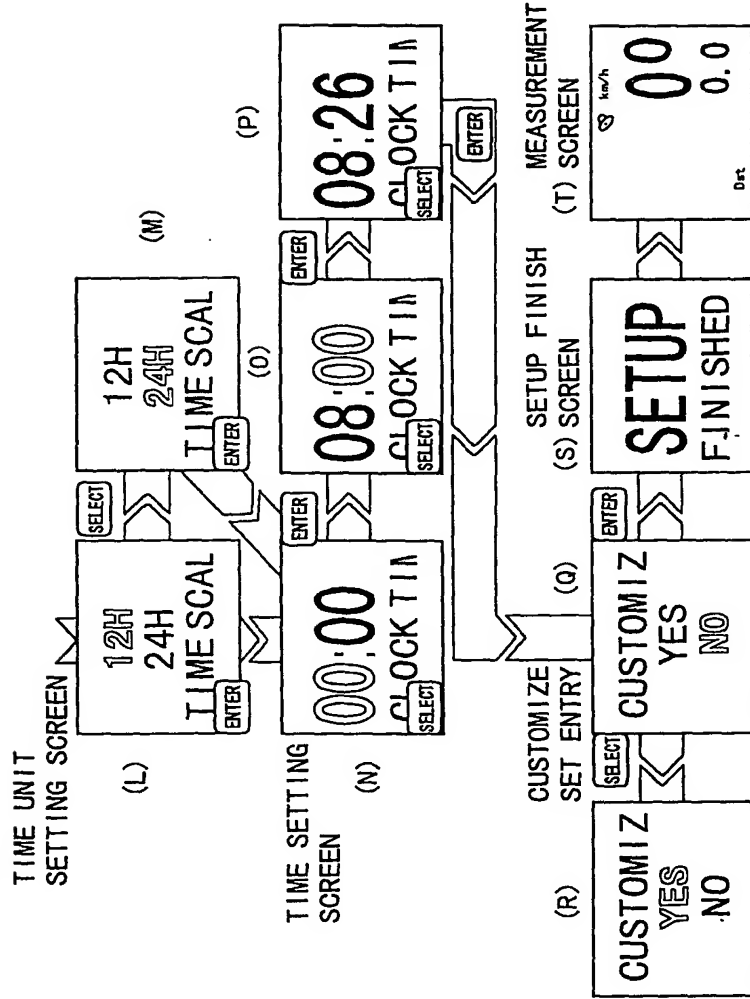


FIG. 8





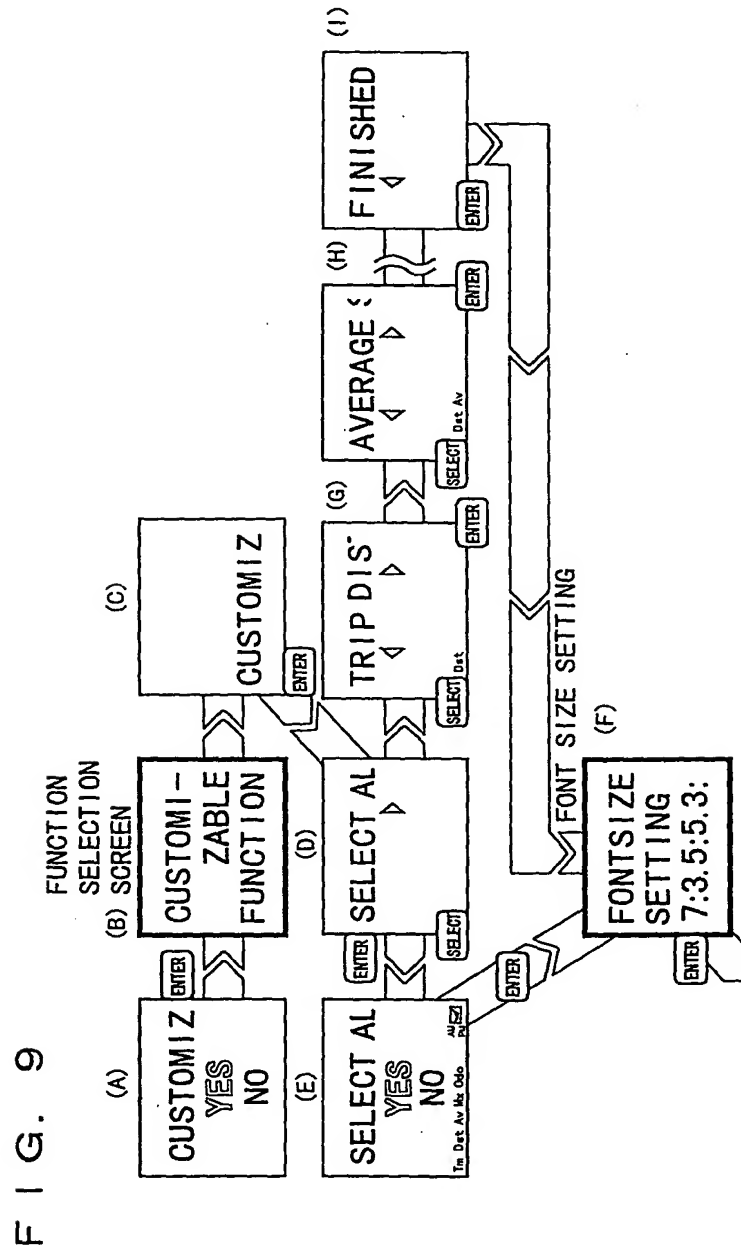
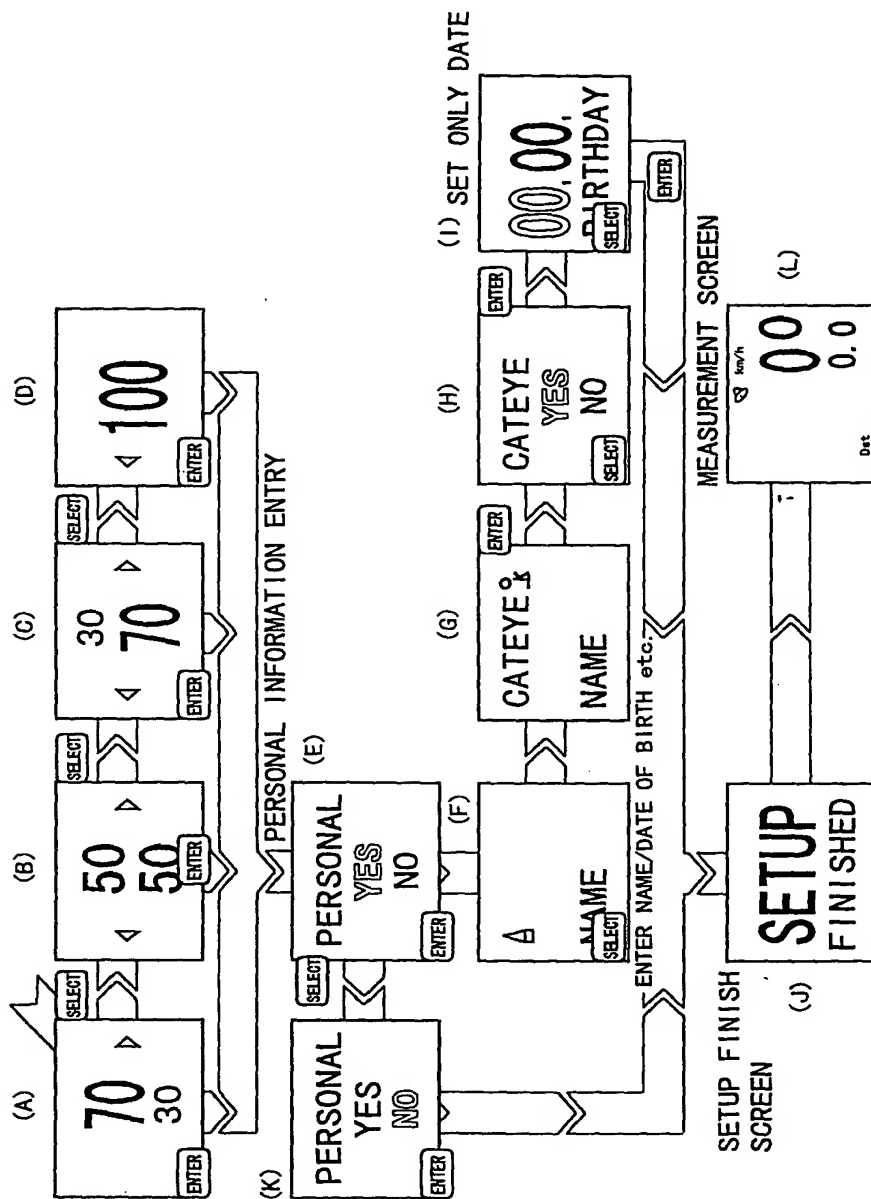


FIG. 10

SELECT ALL  
ELAPSED TIME  
TRIP DISTANCE  
AVERAGE SPEED  
MAXIMUM SPEED  
TOTAL DISTANCE  
CLOCK TIME  
FINISHED

FIG. 11



The flowchart illustrates the sequence of screens in a motorcycle's menu system. It begins with the **GENERAL MEASUREMENT SCREEN**, which leads to the **DATA REVIEW** screen. From there, the user can enter the **LAST RIDE** screen. This screen allows navigation to various data points: **LAST RIDE DAY DATA** (73.8km, '00.05.03), **PAST MAXIMUM SPEED** (63.5km, '00.05.03), **YEARLY MILEAGE** (1998: 2845km), **MONTHLY MILEAGE** (Nov: 156.9km), and **WEEKLY MILEAGE** (Mon: 35.4km). Each of these data points has a corresponding **VERIFY SCREEN** with a bar graph and a date/time display. The flowchart also shows a **MENU VERIFY SCREEN** and a **SELECT** path that loops back to the **LAST RIDE** screen.

```

graph TD
    GMS[GENERAL MEASUREMENT SCREEN] -- MENU --> DR[DATA REVIEW]
    DR -- ENTER --> LRS[LAST RIDE]
    LRS -- ENTER --> LRDD[LAST RIDE DAY DATA  
73.8km  
'00.05.03]
    LRS -- ENTER --> PMS[PAST MAXIMUM SPEED  
63.5km  
'00.05.03]
    LRS -- ENTER --> YMI[YEARLY MILEAGE  
1998  
2845km]
    LRS -- ENTER --> MMI[MONTHLY MILEAGE  
Nov  
156.9km]
    LRS -- ENTER --> WMI[WEEKLY MILEAGE  
Mon  
35.4km]
    LRDD -- SELECT --> LRDDV[DIS  
26.8km  
'00.05.03]
    PMS -- SELECT --> PMSV[ ]
    YMI -- SELECT --> YMIV[ ]
    MMI -- SELECT --> MMIV[ ]
    WMI -- SELECT --> WMIV[ ]
    LRS -- SELECT --> MVS[MENU VERIFY SCREEN]
    MVS -- SELECT --> LRS
    
```

FIG. 13

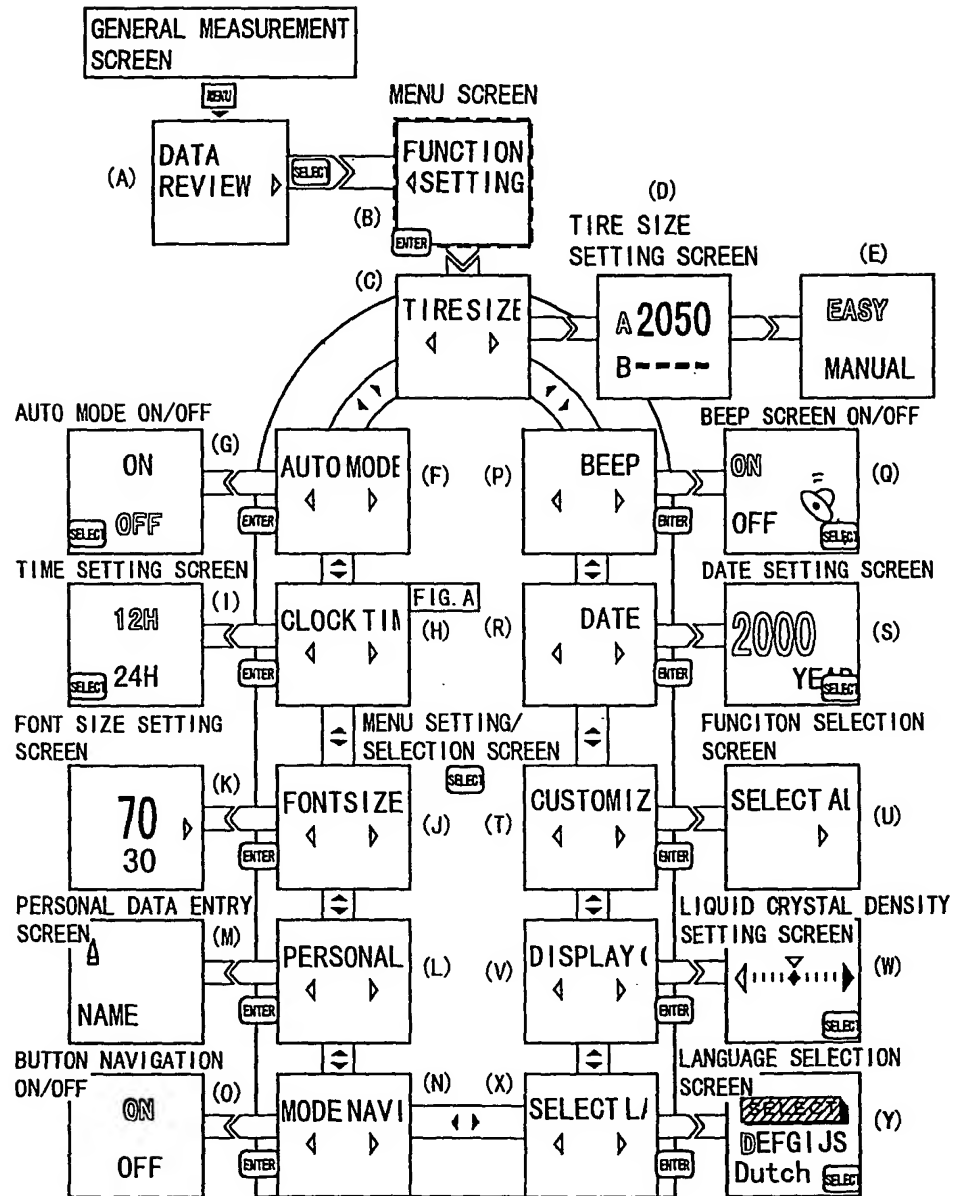


FIG. 14

FORMAT OPERATION

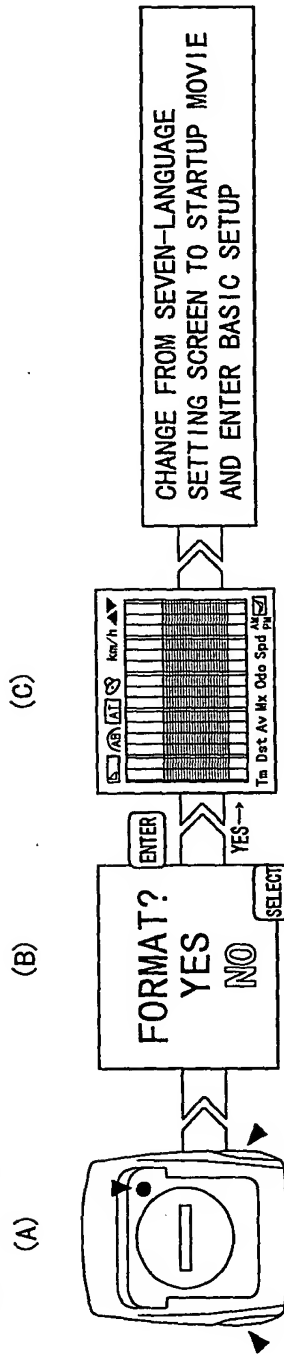


FIG. 15

MODE NAVIGATION OPERATION

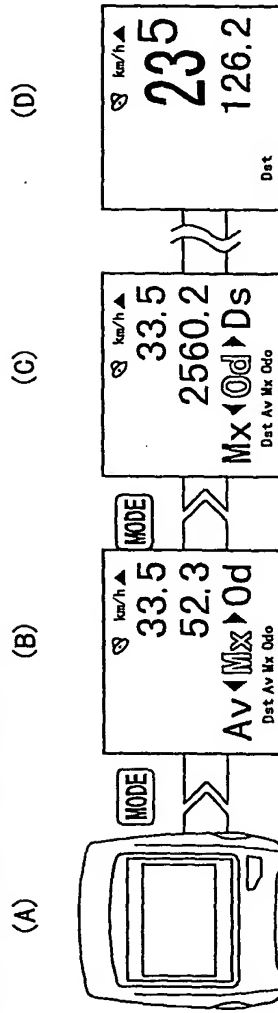
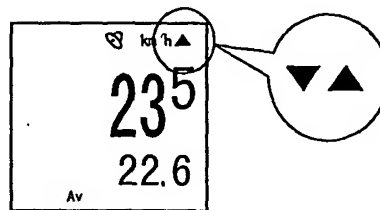


FIG. 16A

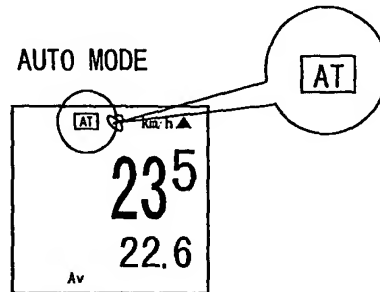
PAGER



DISPLAY WHETHER CURRENT SPEED IS IN  
EXCESS OR BELOW AVERAGE SPEED WITH ARROW

FIG. 16B

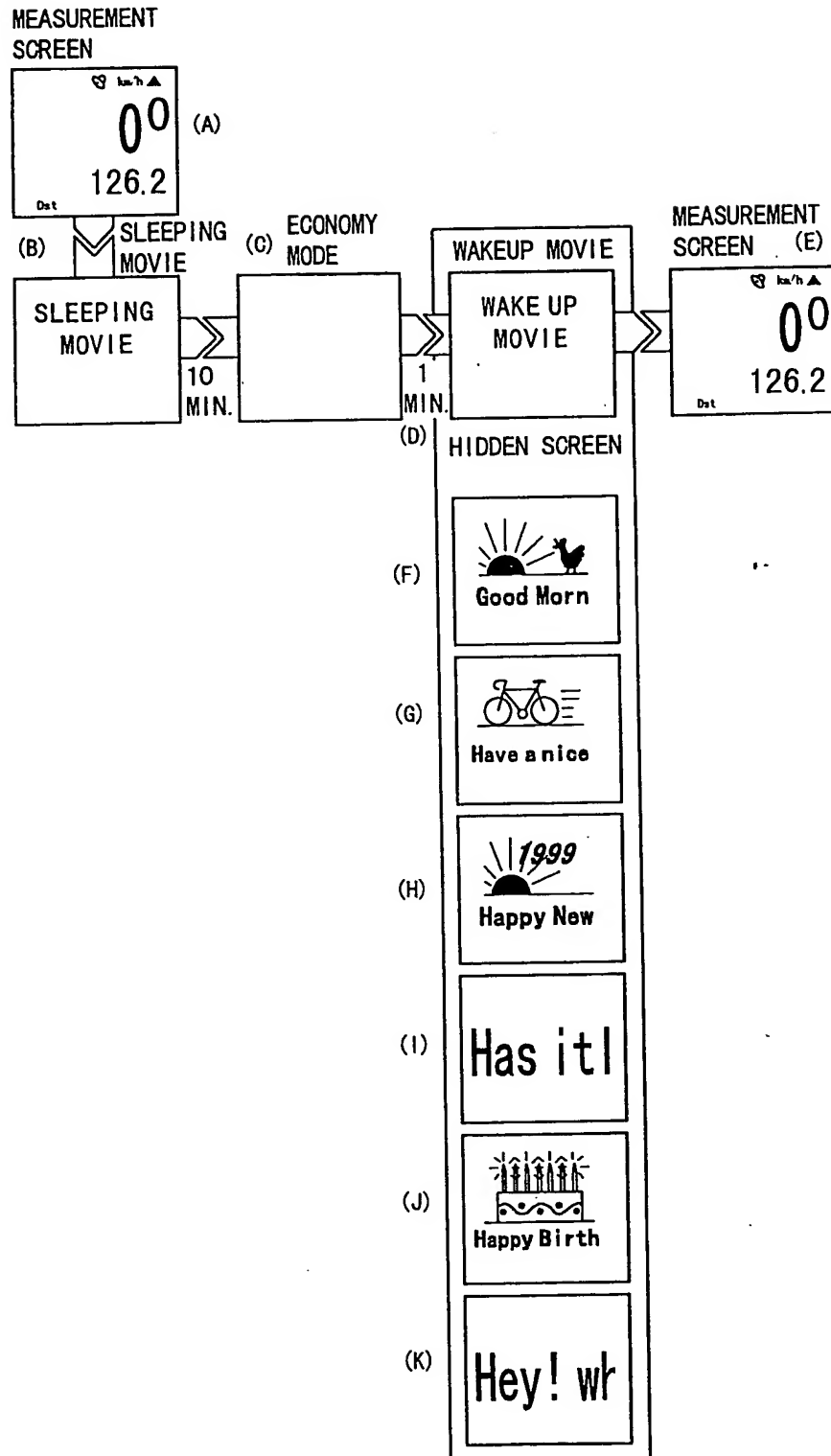
AUTO MODE



AUTOMATICALLY MEASURE WHEN RECEIVING  
SIGNAL WITHOUT START/STOP OPERATION



FIG. 17



F I G. 1 8

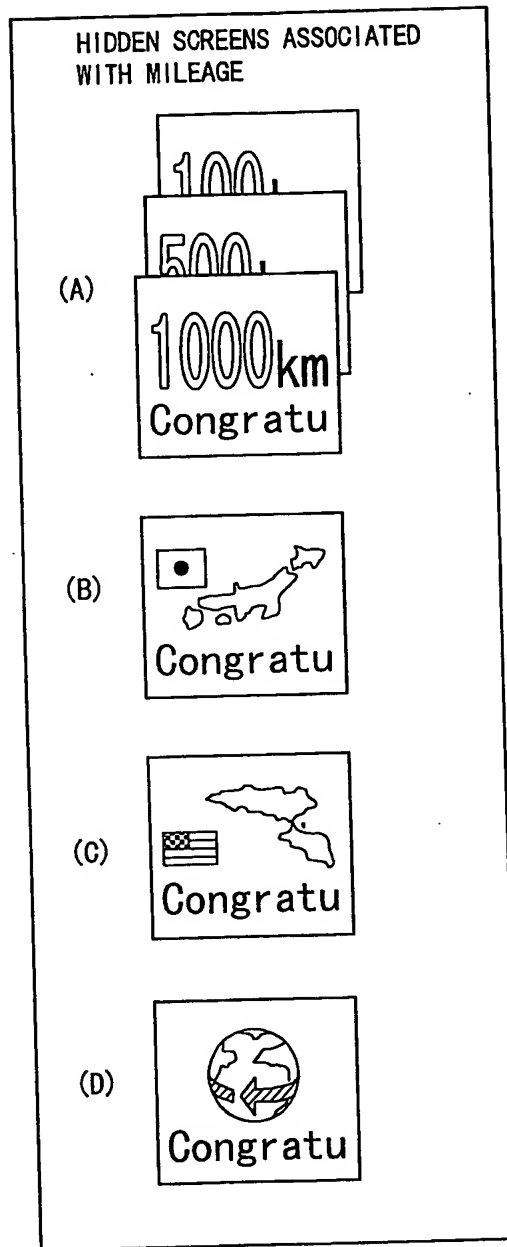


FIG. 19

